

HIGH-SPEED, SPACE-SAVING DESIGN



ES165RD II ES200RD II

MATERIAL HANDLING | MACHINE TENDING | PRESS TENDING

KEY BENEFITS

Versatile, high-performance robot for heavy-payload machine or press tending and other handling tasks

Enhanced safety with control reliable software for guarding (FSU)

Energy efficient design of DX200 versus previous controllers

SPECIFICATIONS

165 kg payload (ES165RD II) 200 kg payload (ES200RD II) 3,140 mm horizontal reach 4,782 mm vertical reach ±0.2 mm repeatability

CONTROLLERS





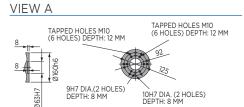


MLX200

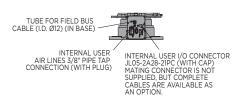
- High-speed six-axis ES165RD II and ES200RD II shelf-mounted robots set standard for versatility in large robot market.
- Designed to provide superior performance in machine and press tending, and other heavy-payload applications.
- Used for loading and unloading of parts, these robots can help eliminate inconsistencies of a manual process for applications such as turning, milling and grinding.
- Ideal for "jigless" applications where robot positions parts for processing by other robots, or two robots handle a single part.
- Ability to handle all types of material including ceramics, composites, metals and polymers.
- Shelf mounting saves floorspace, expands work envelope and improves access to parts.
- Compact, slim design allows robots to reduce cycle time and reach into confined spaces, improving system productivity.

- Large work envelope and high moment of inertia ratings accommodate a wide range of large, heavy parts.
- Fast axial speeds and acceleration reduce cycle times and increase production output.
- Pre-wired for servo gripper use, which allows a wider range of product handling.
- Robust controller integration provides enhanced safety and Functional Safety Unit (FSU) through control reliable safeguarding within the robot software.
- Up to 70% less power consumption during motion and 25% savings during idle periods compared to previous models.
- Cables and air line for end effector are routed through robot base to upper arm to increase cable life, enhance safety and reduce teaching time.
- Floor-mounted versions (ES165D II and ES200D II) available.

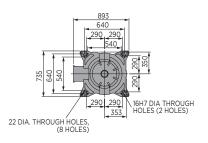
ES165RD II | ES200RD II 2850 2293 \1150 250 153 TUBE FOR FIELD BUS CABLE (I.D. Ø12) (IN PROTECTIVE TUBING) 746 TUBE FOR FIELD BUS CABLE (I.D. Ø12) (IN BASE) INTERNAL USER I/O CONNECTOR JL.05-6A18-1P (WITH CAP). MATING CONNECTOR IS NOT SUPPLIED, BUT COMPLETE CABLES ARE AVAILABLE AS AN OPTION. (C) 22 1225 456 INTERNAL USER AIR LINE 3/8" PIPE TAP CONNECTION (WITH PLUG) 310 3140 732 1107 R3140 TUBE FOR FIELD BUS CABLE (I.D. Ø12) (IN PROTECTIVE TUBING)



VIEW B



VIEW C

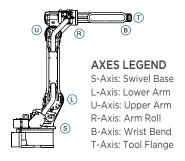


All dimensions are metric (mm) and for reference only. Request detailed drawings for all design/engineering requirements.

SPECIFICATIONS: ES165RD II ES200RD II											
Axes	Maximum		Maximum		Allowable		Allowable moment of inertia [kg•m²]			ES165RD II	ES200RD II
	motion range [°]		speed [°/sec.]		moment [N•m]				Controlled axes	6	6
	ES165RD II	ES200RD II	ES165RD II	ES200RD II	ES165RD II	ES200RD II	ES165RD II	ES200RD II	Maximum payload [kg]	165	200
									Repeatability [mm]	±0.2	±0.2
S	±180	±180	105	90	-	-	-	-	Horizontal reach [mm]	3,140	3,140
L	+80/-130	+80/-130	105	85	-	-	-	-	Vertical reach [mm]	4,782	4,782
U	+208/-112	+208/-107	105	85	-	-	-	-	Temperature [°C]	0 to +45	0 to +45
R	±360	±360	175	120	921	1,344	85	143	Humidity [%]	20 - 80	20 - 80
В	±130	±125	150	120	921	1,344	85	143	Weight [kg]	1,730	1,800
Т	±360	±360	240	190	490	715	45	80	Power supply, average [kVA]	5	5

OPTIONS

Extended length manipulator cables
Robot risers and base plates
Wide variety of fieldbus cards
MotoSight™ 2D and 3D vision systems
Robot base and upper arm I/O cables



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