

GP12

Efficient, High-Speed Robot

Key Benefits

Highest payload, speeds and wrist allowable moment in its class

Space-efficient design

Engineered for easy installation, operation and maintenance

Specifications

12 kg payload 1,440 mm horizontal reach 2,511 mm vertical reach ±0.08 mm repeatability

Applications

Assembly

Material Handling

Packaging



- Increase your productivity with the fast and efficient GP12 robot
- All axis speeds have been increased by up to 15% surpassing other robots in its class
- Reduced interference design allows close proximity placement of robots
- Maximum reduction of acceleration/ deceleration times for all robot positions
- Hollow arm structure eliminates cable interference
- Highest wrist allowable moment for accurate and repeatable handling
- Higher payload allows wider range of tooling integration such as double gripper for multi-handling operations
- IP67-rated wrist and IP54 body (IP65 optional)
- Easy, single cable connection for fast setup and simple maintenance

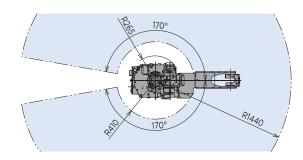
- Equipped with data saving feature that permits the robot's wire harness to be replaced without having to connect it to a battery
- Ideal for high-volume assembly, handling and packaging applications
- The GP-series robots are controlled by Yaskawa's new high-performance YRC1000 controller that is built to a global standard and does not require a transformer for input voltages ranging from 380VAC to 480VAC. It is highly compact, resulting in reduced space requirements. Its I/O communication speed is improved by as much as 50% for improved work efficiency.

GP12 Robot

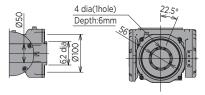
Air exhaust Rc3/8 with pipe plug(A)

Main key (Upper side)

Internal user I/O connector type is JL05-2A20-29SC (with cap). Matching connector type is JL05-6A20-29P (provided users)



VIEW A



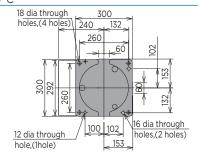
VIEW B



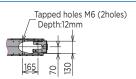
Internal User Air Line Rc3/8 with pipe plug(A)

Internal user wiring connector type is JL05-2A20-29PC (with cap) Matching connector type is JL05-6A20-29S (provided users)

VIEW C



VIEW D



All dimensions are metric (mm) and for reference only. Request detailed drawings for all design/engineering requirements.

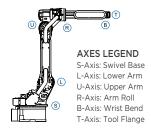
SPECIFICATIONS				
Axes	Maximum motion range [°]	Maximum speed [°/sec.]	Allowable moment [N•m]	Allowable moment of inertia [kg•m²]
S	±170	260	-	-
L	+155/-90	230	-	-
U	+150/-85	260	-	-
R	±200	470	22	0.65
В	±150	470	22	0.65
Т	±455	700	9.8	0.17

Mounting Options: Floor, Wall, or Ceiling

Item	GP12			
Controlled axes	6			
Maximum payload [kg]	12			
Repeatability [mm]	±0.08			
Horizontal reach [mm]	1,440			
Vertical reach [mm]	2,511			
Weight [kg]	130			
Internal user I/O cable	17 conductors (+ ground)			
Internal user air line	(1) 3/8" connection			
Power requirements	380-480 VAC			
Power rating [kVA]	1.5			

Options

- Robot risers and base plates
- MotoSight[™] 2D and 3D vision systems



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