

# MH280 II

MATERIAL HANDLING | MACHINE TENDING | PRESS TENDING

### KEY BENEFITS

Small mounting surface and minimum interference radius save valuable floorspace

Optimized robot design with increased speed reduces cycle time

Increased payload, moment and inertia ratings allow use for wide variety of applications

Slim wrist profile for high density spacing and for reaching into confined spaces

### SPECIFICATIONS

280 kg payload

2,446 mm horizontal reach

2,962 mm vertical reach

±0.2 mm repeatability

Floor mounted

### CONTROLLERS



DX200



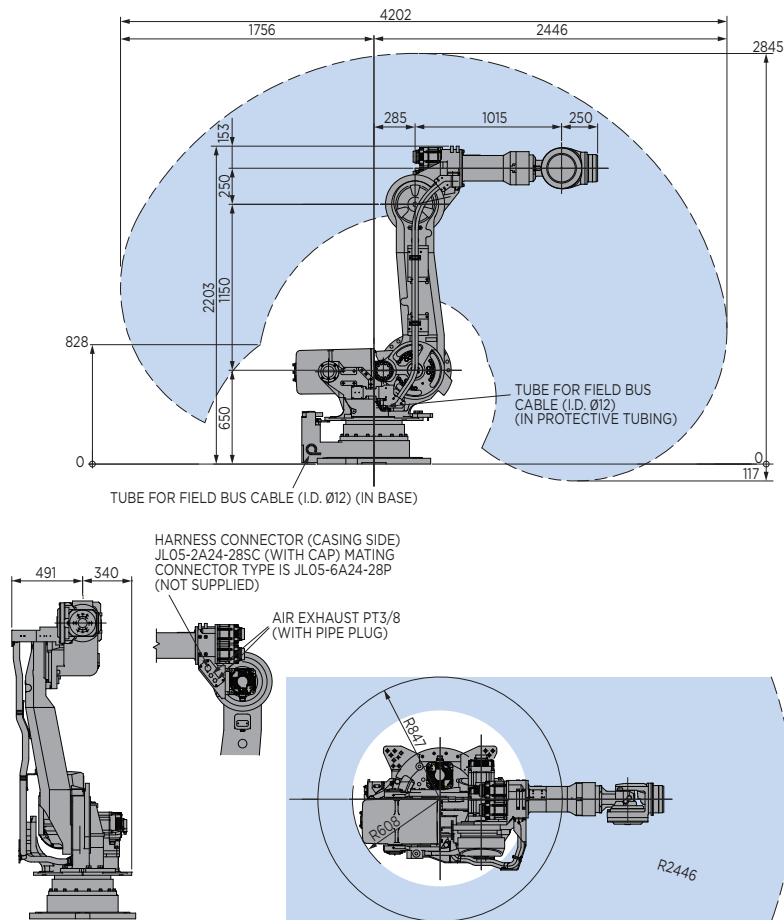
FS100



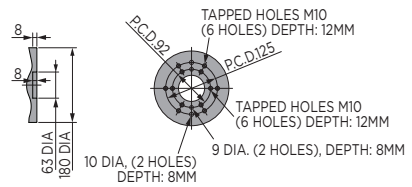
MLX200

- The powerful, heavy-payload MH280 II is ideal for one of the most common robotics applications today – machine tending.
- From boring to milling to grinding, the MH280 II can help improve product quality by removing inconsistencies of a manual process and deliver cost-saving benefits to metal, polymer, ceramic and composite manufacturers.
- Ideal for “jigless” applications where robot positions parts for processing by other robots, or two robots handle a single part.
- The high-speed, six-axis MH280 II robot is designed to provide superior performance, reliability and flexibility.
- High-rigidity speed reducers and high-speed motion reduce cycle times.
- Streamlined upper arm design allows easier reach into confined spaces, improving application flexibility.
- Large work envelope extends behind body (due to no counterbalance), providing a wider range of motion which can increase the number of operations in a single cell and accommodating a wide range of big, heavy parts.
- Up to 70% less power consumption during motion and 25% savings during idle periods compared to previous models.
- Cables and air lines for end effector are routed through robot base to upper arm to increase cable life, enhance safety and reduce teaching time.

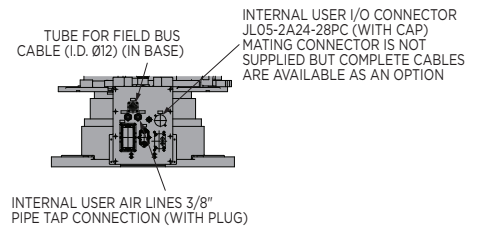
# MH280 II ROBOTS



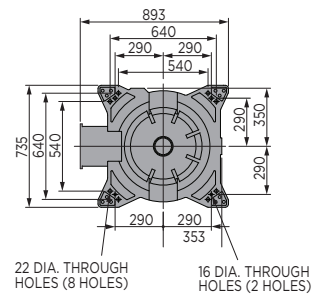
## VIEW A



## VIEW B



## VIEW C



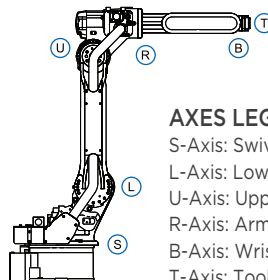
All dimensions are metric (mm) and for reference only. Request detailed drawings for all design/engineering requirements.

## SPECIFICATIONS: MH280 II

Axes	Maximum motion range [°]	Maximum speed [°/sec.]	Allowable moment [N·m]	Allowable moment of inertia [kg·m <sup>2</sup> ]	Controlled axes	6
S	±180	90	-	-	Maximum payload [kg]	280
L	+76/-60	80	-	-	Repeatability [mm]	±0.2
U	+230/-142.5	90	-	-	Horizontal reach [mm]	2,446
R	±360	115	1,333	142	Vertical reach [mm]	2,962
B	±125	110	1,333	142	Temperature [°C]	0 to +45
T	±360	190	706	79	Humidity [%]	20 - 80
					Weight [kg]	1,120
					Power supply, average [kVA]	5.0
					Internal I/O cable [conductors w/ ground]	24
					Internal air line [connections]	(2) 3/8"

## OPTIONS

- Extended length manipulator cables
- Robot risers and base plates
- External axis kits
- Wide variety of fieldbus cards
- Vision systems
- Robot base and upper arm I/O cables



### AXES LEGEND

- S-Axis: Swivel Base
- L-Axis: Lower Arm
- U-Axis: Upper Arm
- R-Axis: Arm Roll
- B-Axis: Wrist Bend
- T-Axis: Tool Flange

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