

## **KEY BENEFITS**

High-speed, 4-axis palletizing robot with performance-driven design

High allowable moment of inertia handles unbalanced loads effectively

Highly reliable

#### **SPECIFICATIONS**

500 kg maximum payload 3,024 mm vertical reach 3,159 mm horizontal reach ±0.5 mm repeatability

### **CONTROLLERS**



DX200





FS100



- Highly versatile, this 4-axis robot is ideal for a variety of palletizing applications, order picking and other logistical tasks for end-of-line or distribution center automation.
- Extensive 3,024 mm vertical reach combined with 3,159 mm horizontal reach enables this robot to build 102 in. tall trailer-high loads on standard 48 in. x 40 in. pallet.
- Hollow wrist provides a wide range of wrist motion without interference.
- T-axis features high allowable moment of inertia; asymmetric loads are handled effectively without compromising speed or performance.
- Internally routed airlines and cables from base to the end-of-arm tool maximizes reliability.

- Cable installation tube in robot base facilitates fieldbus routing to the upper arm and/or gripper.
- Available with PalletSolver<sup>™</sup>,
   Yaskawa Motoman's operator-friendly
   palletizing software suite for fast and
   easy creation of palletizing patterns.
  - PalletSolver's offline pattern generation tool with intuitive graphical interface allows quick changeovers without halting production.
  - Highly customizable to each palletizing system.
  - Directly imports pallet patterns generated in widely-used TOPS® or CAPE software.

## MPL500 II ROBOT VIEW A 2204 P-POINT T -POINT 2624 320 2529 2363 \_Ø12 THRU 8X Ø22 THRU-VIEW B 820 3159 T-POINT MAXIMUM ENVELOPE 7 80 PCD200. -12X M12X1.75 x 18 Ø10 x10 1600 1300 VIEW C 1391 TUBE FOR FIELDBUS CABLE (I.D. Ø12) (IN BASE) 1600 INTERNAL USER AIR HOSE PT 3/8" WITH PIPE PLUG INTERNAL USER CABLE CONNECTOR JL05-2A24-28PC (WITH CAP) MATING CONNECTOR JL05-6A24-28S WILL NOT BE SUPPLIED.BUT CABLES ARE AVAILABLE AS AN OPTION. R3159 ~ R1037

All dimensions are metric (mm) and for reference only. Request detailed drawings for all design/engineering requirements.

SPECIFICATIONS						
A	Maximum	Maximum speed	Allowable	Allowable moment of	Controlled axes	4
Axes	motion range [°]	[°/sec.]	moment [N•m]	inertia [kg•m²]	Maximum payload [kg]	500
S	±180	85	-	-	Repeatability [mm]	±0.5
					Horizontal reach [mm]	3,159
L	+90/-45	85	-	-	Vertical reach [mm]	3,024
					Protection (IP rating)	IP54
U	+15.5/-120	85	-	-	Weight [kg]	2,300
					Power requirements	3-phase; 240/480/575 VAC at 50/60 Hz
Т	±360	195	-	200	Power rating [kVA]	8.0

# **OPTIONS**

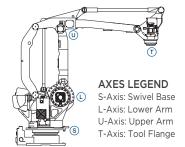
Extended length manipulator cables

PalletSolver - revolutionary palletizing software

MotoSight™ - easy to integrate vision software

Robot risers and base plates

Wide variety of fieldbus connectivity



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