IRB 140 Industrial Robot

Main Applications

Arc welding Assembly Cleaning/Spraying Machine tending Material handling Packing Deburring



Small, Powerful and Fast

Compact, powerful IRB 140 industrial robot.

Six axis multipurpose robot that handles payload of 6 kg, with long reach (810 mm). The IRB 140 can be floor mounted, inverted or on the wall in any angle. Available as Standard, Foundry Plus 2, Clean Room and Wash versions, all mechanical arms completely IP67 protected, making IRB 140 easy to integrate in and suitable for a variety of applications. Uniquely extended radius of working area due to bend-back mechanism of upper arm, axis 1 rotation of 360 degrees even as wall mounted.

The compact, robust design with integrated cabling adds to overall flexibility. The Collision Detection option with full path retraction makes robot reliable and safe. Using IRB 140T, cycle-times are considerably reduced where axis 1 and 2 predominantly are used.

Reductions between 15-20 % are possible using pure axis 1 and 2 movements. This faster versions is well suited for packing applications and guided operations together with PickMaster.

IRB 140 Foundry Plus 2 and Wash versions are suitable for operating in extreme foundry environments and other harch environments with high requirements on corrosion resistance and tightness. In addition to the IP67 protection, excellent surface treatment makes the robot high pressure steam washable. Also available in white Clean Room ISO class 6 version, making it especially suited for environments with stringent cleanliness standards.



IRB 140

Specification				Electrical Connections	
Robot versions	Handling	Reach of	Remarks	Supply voltage	200–600 V, 50/60 Hz
	capacity	5th axis		Rated power	
IRB 140/IRB 140T	6 kg	810 mm		Transformer rating	4.5 kVA
IRB 140F/IRB 140TF	6 kg	810 mm	Foundry Plus 2 Protection	Power consumption typicly	0.4 kW
IRB 140CR/IRB 140TCF	l 6 kg	810 mm	Clean Room	Physical	
IRB 140W/IRB 140TW	6 kg	810 mm	SteamWash Protection	Robot mounting	Any angle
Supplementary load (on upper arm alt. wrist)				Dimensions	
on upper arm		1 kg		Robot base	400 x 450 mm
on wrist		0.5 kg		Robot controller H x W x D	950 x 800 x 620 mm
Number of axes				Weight	
Robot manipulator		6		Robot manipulator	98 kg
External devices		6		Environment	
Integrated signal supply	grated signal supply 12 signals on upper arm			Ambient temperature for	
Integrated air supply		r on upper a		Robot manipulator	5 – 45°C
IRC5 Controller variants:	Single cat	pinet, Dual ca	binet, Compact,	Relative humidity	Max. 95%
	Panel mou	unted		Degree of protection,	
Performance				Manipulator	IP67
Position repeatability 0.03 mm (average result from ISO 1			rom ISO test)	Options	Foundry Plus 2
Axis movement	Axis		Working range		SteamWash
	1		360°		(High pressure steam washable)
	2		200°		Clean Room, class 6
	3		280°		(certified by IPA)
	4		Unlimited (400° default)	Noise level	Max. 70 dB (A)
	5		230°	Safety	Double circuits with supervision,
	6		Unlimited (800° default)		emergency stops and safety
Max. TCP velocity			2.5 m/s		functions,
Max. TCP acceleration			20 m/s ²		3-position enable device
Acceleration time 0-1 m	/s		0.15 sec	Emission	EMC/EMI-shielded
Velocity *)				Data and dimensions may be changed without notice	
Axis no.	IRB 14	0	IRB 140T		
1	200°/s		250°/s		
2	200°/s		250°/s	Working range	
3	260°/s		260°/s		
4	360°/s		360°/s		
5	360°/s		360°/s		
6	450°/s		450°/s	380 65	15
*) Max velocity is reduce	d at single	phase power	supply, e.g. Compact	1092	670
controller. Please, see th	e Product s	specification	for further details.		
Cycle time				712	
5 kg Picking side	IRB 14	0	IRB 140T		70
cycle 25 x 300 x 25 mm	0.85s		0.77s	350	810
				151	486

6 kg

2 kg

100 150 L-distance (mm)

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